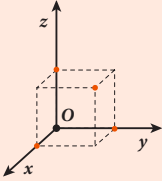
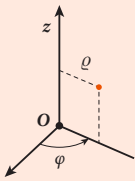
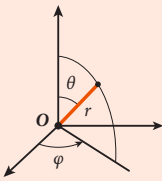


Coordinate cartesiane, cilindriche e polari

	Coordinate cartesiane (x, y, z)	Coordinate cilindriche (ϱ, φ, z)	Coordinate polari (r, θ, φ)
			
$d\vec{l}$	dx, dy, dz	$d\varrho, \varrho d\varphi, dz$	$dr, r d\theta, r \text{sen}\theta d\varphi$
grad f	$(\nabla f)_x = \frac{\partial f}{\partial x}$ $(\nabla f)_y = \frac{\partial f}{\partial y}$ $(\nabla f)_z = \frac{\partial f}{\partial z}$	$(\nabla f)_\varrho = \frac{\partial f}{\partial \varrho}$ $(\nabla f)_\varphi = \frac{1}{\varrho} \frac{\partial f}{\partial \varphi}$ $(\nabla f)_z = \frac{\partial f}{\partial z}$	$(\nabla f)_r = \frac{\partial f}{\partial r}$ $(\nabla f)_\theta = \frac{1}{r} \frac{\partial f}{\partial \theta}$ $(\nabla f)_\varphi = \frac{1}{r \text{sen}\theta} \frac{\partial f}{\partial \varphi}$
div \vec{v}	$\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$	$\frac{1}{\varrho} \frac{\partial(\varrho v_\varrho)}{\partial \varrho} + \frac{1}{\varrho} \frac{\partial v_\varphi}{\partial \varphi} + \frac{\partial v_z}{\partial z}$	$\frac{1}{r^2} \frac{\partial(r^2 v_r)}{\partial r} + \frac{1}{r \text{sen}\theta} \frac{\partial(\text{sen}\theta v_\theta)}{\partial \theta} + \frac{1}{r \text{sen}\theta} \frac{\partial v_\varphi}{\partial \varphi}$
rot \vec{v}	$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$	$(\text{rot } \vec{v})_\varrho = \left(\frac{1}{\varrho} \frac{\partial v_z}{\partial \varphi} - \frac{\partial v_\varphi}{\partial z} \right)$ $(\text{rot } \vec{v})_\varphi = \left(\frac{\partial v_\varrho}{\partial z} - \frac{\partial v_z}{\partial \varrho} \right)$ <div style="border: 1px solid red; padding: 5px; display: inline-block;">$(\text{rot } \vec{v})_z = \frac{1}{\varrho} \left(\frac{\partial(\varrho v_\varphi)}{\partial \varrho} - \frac{\partial v_\varrho}{\partial \varphi} \right)$</div>	$(\text{rot } \vec{v})_r = \frac{1}{r \text{sen}\theta} \left(\frac{\partial(\text{sen}\theta \cdot v_\varphi)}{\partial \theta} - \frac{\partial v_\theta}{\partial \varphi} \right)$ $(\text{rot } \vec{v})_\theta = \frac{1}{r \text{sen}\theta} \frac{\partial v_r}{\partial \varphi} - \frac{1}{r} \frac{\partial(r v_\varphi)}{\partial r}$ $(\text{rot } \vec{v})_\varphi = \frac{1}{r} \left(\frac{\partial(r v_\theta)}{\partial r} - \frac{\partial v_r}{\partial \theta} \right)$